

#### **FACTORY OF ELECTRIC APPARATUS**

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## ELECTROMAGNETIC DISC BRAKES HPSX SERIES WITH REGULATING BRAKING TORQUE









Spring actuated and electromagnetically released disk brake type HPSX powered by direct current. Designed for braking rotating machine parts and their precision positioning. Utilized as safety brake. High repeatability even with large number of actuations. The brake characterizes relatively simple construction, facility for regulating brake parameters such as braking torque, braking time and also possibility of supply from alternating current source after connecting up a rectifier circuit delivered at customer's request along with the brake. An additional feature is quiet operation, particularly important when the equipment is operated by a number of drives operating additionally with high frequency of actuations. Braking torque can be accurately set by means of regulating nut. Brake design guarantees simple and problem-free installation. Various options of executions are at disposal with respect to fittings/accessories, brake supply, climatic conditions of utilization, enabling selection of appropriate option for definite utilization conditions.



### They are designed for braking rotating parts of machines and their task is:

- emergency stopping, in order to ensure drive safety functions,
- immobilizing machine actuators, acting as a positioning device,
- minimizing run-on times of drives (to meed safety requirements according to Office of Technical Inspection (UDT) regulations,
- built onto an electric motor, the brake provides a self-braking motor, a drive unit meeting the requirements of utilisation safety and positioning.

Brakes can be manufactured in variants suitable for various direct-current voltages: 24V, 104V, 180V, 207V which allows them to be supplied from standard alternating current sources, through appropriate rectifier.

								Brake type	)				
	Parameters		Unit	HPSX 06	HPSX 08	HPSX 10	HPSX 12	HPSX 14	HPSX 16	HPSX 18	HPSX 20	HPSX 25	
Supply voltage Un			[V]		24 , 104 , 180 , 207 VDC								
Pow	ver	P <sub>20°</sub>	[W]	20	25	30	40	50	55	65	75	130	
Bra	Braking torque M		[Nm]	7	13	26	50	100	160	240	400	800	
Max. speed n <sub>max.</sub>			min <sup>-1</sup>		3000								
Wei	Weight		kg	0,8	2,0	3,6	6,9	8,0	12,0	18,3	25,5	30,5	
	bient perature		°C	-25 ÷ +40									
*	On direct	$t_{0,1}$	<b>12</b> 00	35	65	90	120	150	180	300	400	500	
time	voltage side	t <sub>0,9</sub>	ms	17	35	40	50	65	90	110	200	270	
	to	t <sub>0,1</sub>		35	65	90	120	150	180	300	400	500	
Operating		t <sub>0,9</sub>	ms	Brake				current sid				wth in	

t<sub>0,1</sub> - releasing time (from switching on current to drop in braking torque to 10% M<sub>nom</sub>)

t<sub>0,9</sub> - braking time (from switching off current to attaining 90% M<sub>nom</sub>)

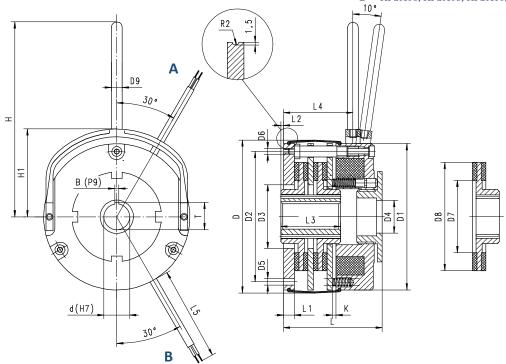
Page 2 from 8 K-EN-HPSX-20151203

<sup>\*)</sup> Values of releasing and braking times are given as approximations, since they depend on mode of assembly/installation, temperature and power supply.



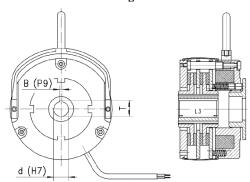
A - HPSX12, HPSX14, HPSX16, HPSX18, HPSX20

B – HPSX06, HPSX08, HPSX10, HPSX25



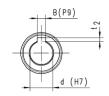
Type	M <sub>h</sub> [Nm]	D	D1	D2	D3	D4	D5	D6	D7	D8	D9	L	L1	L2	L3	L4	L5	L6	K	Н	H1
HPSX06	7	87	84	72	25	17	4,5x3	M4x3	47	62	8	52	6	0	25	37	450	6,7	0,2	100	51
HPSX08	13	106	102	90	40	17	5,5x3	M5x3	59	76	8	68	7	4	48	40	450	6,7	0,2	111	61
HPSX10	26	132	125	112	44	21	6,4x3	M6x3	61	95	10	82	9	3	55	53	450	9,0	0,2	160	73
HPSX12	50	157	148	132	45	27	6,4x3	M6x3	74	114	10	94	9	5	65	59	450	9,0	0,3	181	94
HPSX14	100	169	162	145	55	27	8,4x3	M8x3	90	124	12	106	11	8	75	63	450	9,0	0,3	193	102
HPSX16	160	195	188	170	84	38	8,4x3	M8x3	100	154	12	112	11	8	75	63	450	9,0	0,3	206	116
HPSX18	240	221	215	196	104	43	9,0x4	M8x6	130	176	12	134	11	16	92	82	450	11,0	0,3	237	129
HPSX20	400	257	252	230	134	45	11x6	M10x6	148	207	14	154	11	16	105	94	450	11,0	0,5	339	157
HPSX25	800	308	302	278	120	45	11x6	M10x6	198	255	14	168	12,5	19	115	113	450	11,0	0,5	466	182

#### Geared bushing hole diameters



Type	d	В	T	d max	d smax *	L3
HPSX06	15	5	17,3	15		25
HPSX08	15	5	17,3	15		48
HPSX10	19	6	21,8	25		55
HPSX12	25	8	28,3	25		65
HPSX14	25	8	28,3	35**		75
HPSX16	35**	8	38,3	35**		75
HPSX18	40	12	43,3	45	50	92
HPSX20	42	12	45,3	45	50	105
HPSX25	42	12	45,3	45	75	115

#### Normalized hole diameter ranges



Hole diameter [mm]	В	t 2
above - to		
10 - 12	4	1,8
12 – 17	5	2,3
17 – 22	6	2,8
22 - 30	8	3,3
30 – 38	10	3,3
38 – 44	12	3,3
44 – 50	14	3,8
50 - 58	16	4,3
58 - 65	18	4,4
65 - 75	20	4,9

d smax - standard geared bushing hole diameters
- maximum geared bushing hole diameters

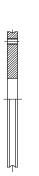
d\* smax - at extra charge it is possible to manufacture the brakes with the specially increased diameter of the gear hub

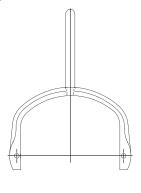
\*\* -for the HPSX14 and HPSX16 brakes and for the geared bushing hole diameters from 32 to 35mm, the key gr

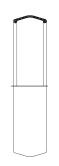
\*\* -for the HPSX14 and HPSX16 brakes and for the geared bushing hole diameters from 32 to 35mm, the key groove with the width of 8 mm (the width of the groove is incompatible with PN/M-85005 and DIN 6885 standards)

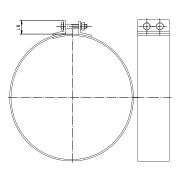
K-EN-HPSX-20151203 Page 3 from 8

#### **BEAKES EQUIPMENT**









Type	L7
HPSX06	11
HPSX08	11
HPSX10	9
HPSX12	11
HPSX14	13
HPSX16	13
HPSX18	13
HPSX20	13
HPSX25	13

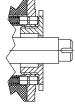
Mounting flange | Lever for manual release

Brake cover

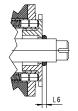
IP56 brake cover



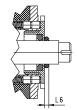
Adjustment nut without a hole



Adjustment nut with a hole



Adjustment nut with a hole and a sealing ring



Adjustment nut with a hole and special packing

#### **ELECTRICAL EQUIPMENT**

A number of modules, ranging from simple circuits with classic designs, to complex assemblies ensuring quick action and drives positioning have been designed to drive the brakes. Relevant brake applications with switching in the primary or secondary circuits are ensured by half- or full-wave rectifiers and fast electronic circuits. The manufacturer recommends to use as low alternating current voltages as possible to supply the brakes. Appropriate choice of the control voltage will prevent or at least limit surges that may occur in power supply circuits. It is not recommended to use extensively long control wiring, which would be a source of harmful surges.

#### **Rectifier B2-1P**

The B2-1P rectifiers series forms a complete wave rectifier unit for direct installation. The terminal strip provided facilitates installation and connection to the circuit.

RECTIFIER PARAMETERS							
		B2-1P-400	B2-1P-600				
Maximum input voltage (alternating voltage AC)	$U_{ m IN}$	400 VAC	600 VAC				
Maximum output voltage (direct voltage DC)	$U_{ m OUT}$	0,45 U <sub>IN</sub>	$0,45U_{\rm IN}$				
Maximum continuous output current rectifier	$I_{ m OUT}$	2A	2A				

#### For example

Maximum input voltage (alternating voltage) -  $U_{IN} = 230 \text{VAC}$ ,

The resulting output voltage of the rectifier (direct voltage) -  $0.45U_{IN}$ =  $0.45 \times 230$ =104VDC

#### **Rectifier B5-1P**

The B5-1P rectifiers series forms a complete wave rectifier unit for direct installation. The terminal strip provided facilitates installation and connection to the circuit.

Rectifier B5-1P cooperates with brakes HPSX06 ÷ HPSX25.

RECTIFIER PARAMETERS							
		B5-1P-400	B5-1P-600				
Maximum input voltage (alternating voltage AC)	$U_{ m IN}$	400 VAC	600 VAC				
Maximum output voltage (direct voltage DC)	$U_{ m OUT}$	$0,45~U_{\mathrm{IN}}$	$0,45U_{\mathrm{IN}}$				
Maximum continuous output current rectifier	I <sub>OUT</sub>	5A	5A				

#### For example

Maximum input voltage (alternating voltage) -  $U_{IN} = 230 \text{VAC}$ ,

The resulting output voltage of the rectifier (direct voltage) -  $0.45U_{IN}$ =  $0.45 \times 230$ =104VDC

K-EN-HPSX-20151203 Page 4 from 8

#### Rectifier B2-2P

The B2–2P rectifiers series forms a complete full-wave rectifier unit for direct installation. The terminal strip provided facilitates installation and connection to the circuit. The rectifier allows feeding input voltage max. 400VAC, 2A which after rectification provides DC voltage of value equal to 0,9 input voltage.

Rectifier B2-2P co	operates with	brakes HPSX06 ÷	HPSX25.

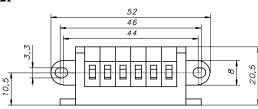
RECTIFIER PARAMETERS						
Maximum input voltage (alternating voltage AC)	$U_{ m IN}$	250 VAC				
Maximum output voltage (direct voltage DC)	$U_{ m OUT}$	$0.9U_{ m IN}$				
Maximum continuous output current rectifier	$I_{ m OUT}$	2A				

#### For example

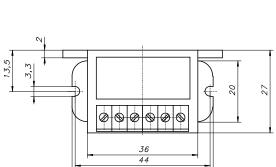
Maximum input voltage (alternating voltage) -  $U_{\rm IN}$  = 230VAC, The resulting output voltage of the rectifier (direct voltage) - 0.9 $U_{\rm IN}$ = 0.9 x 230=207VDC

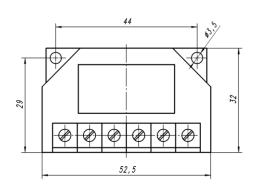
#### **Rectifiers dimensions**

B2-1P-400, B5-1P-400, B2-2P



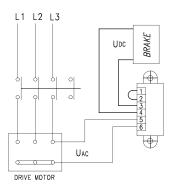






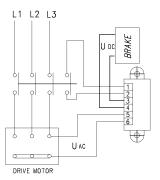
#### Disconnection of power supply on AC side

The diagram presents connection of rectifiers to supply circuit of motor. When disconnecting the voltage, the magnetic field causes the coil current to flow further through the rectifying diodes and drops slowly. The magnetic field reduces gradually causing prolonged time of braking action and consequently delayed increase of braking torque. If action time is irrelevant, brake should be connected on the AC side. When switching off, the supply circuits act as rectifying diodes.



#### Disconnection of power supply on DC side

The diagram presents connection of rectifiers into electric motor circuit. The coil current is interrupted between the coil and supply (rectifier) circuit. The magnetic field reduces very quickly, **giving short time of braking action and consequently rapid growth of braking torque**. When switching off on DC voltage side, a high peak voltage is generated in the coil causing faster wear of contacts due to sparking. For protecting the coil against peak voltages and protecting the contacts against excessive wear, the rectifier circuit is provided with protective facility allowing brake connection on DC voltage side.

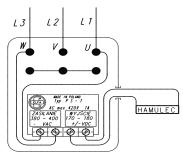


K-EN-HPSX-20151203 Page 5 from 8

#### **Rectifier PS-1**

Circuit PS-1 is built on the basis of MOSFET type semiconductor technique which enabled achieving effects not available in traditional designs. The brake electromagnet energized through circuit of this construction enables the brake to achieve connection and disconnection time parameters analogous to breaking of circuit on direct current side. The parameters obtained are not however gained through utilization of additional electrical circuits and switches.

Simplicity of installation and parameters achieved enable very wide application, particularly in cases requiring positioning of drives, operation with high frequency of actuations compounded with repeatability of brake connecting and disconnecting times.



Supply circuit PS-1 forms a complete unit for direct installation. Provided with a four-terminal strip, it enables unhindered adaptation in every cooperating circuit. The circuit is adapted for supply from alternating current source of 380-400 VAC max. 420 VAC which after rectification and appropriate formation enables obtaining direct voltage of 170-180 VDC for brake supply.

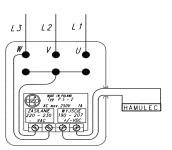
The diagram below shows the method of connecting the circuit PS 1 into supply circuit of brake cooperating with 3x400 VAC electric motor with star-connected winding.

Rectifier PS-1 cooperates with brakes HPSX06 ÷ HPSX20.

#### **Rectifier PS-2**

Circuit PS-2 is built on the basis of MOSFET type semiconductor technique which enabled achieving effects not available in traditional designs. The brake electromagnet energized through circuit of this construction enables the brake to achieve connection and disconnection time parameters analogous to breaking of circuit on direct current side. The parameters obtained are not however gained through utilization of additional electrical circuits and switches.

Simplicity of installation and parameters achieved enable very wide application, particularly in cases requiring positioning of drives, operation with high frequency of actuations compounded with repeatability of brake connecting and disconnecting times.

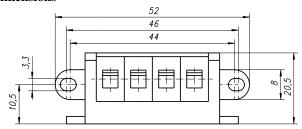


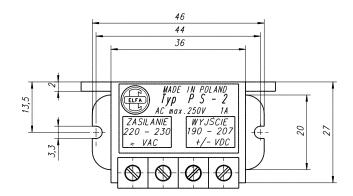
Supply circuit PS 2 forms a complete unit for direct installation. Provided with a four-terminal strip, it enables unhindered adaptation in every cooperating circuit. The circuit is adapted for supply from alternating current source of 220-230 VAC max. 250 VAC which after rectification and appropriate formation enables obtaining direct voltage of 190-207 VDC for brake supply.

The diagram below shows the method of connecting the circuit PS 2 into supply circuit of brake cooperating with 3x400 VAC electric motor with star-connected winding.

Rectifier PS-2 cooperates with brakes HPSX06 ÷ HPSX25.

#### Rectifiers PS-1, PS-2 dimensions



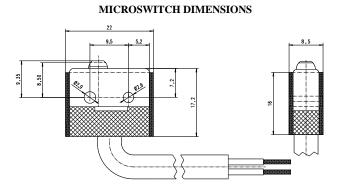


Page 6 from 8 K-EN-HPSX-20151203

#### CONTROL AND SIGNALING CIRCUTS – microswitches

Having in mind the user who requires the control of the brake, we have designed special signaling and control circuits, which enable to control the state of the brake (engaged, disengaged) and the wear of the plate lining. The usage of these circuits enables to control the brake with the use of automatic elements, which ensure high level of safety and reliability. Due to its compact design, the microswitch can be used in any other applications, as long as its parameters meet design requirements.

MICROSWITCHES - ELECTRIC PARAMETERS							
Switch parameter	Switch KZ	Switch KO					
Max. voltage AC	250 V AC	250 V AC					
Max. AC switching current	5 A	6 A					
Max. Voltage DC	28V DC	220V DC					
Max. DC switching current	3 A / 28V DC	6A / 12V DC 3A / 24V DC 1A / 60V DC 0,5A / 110V DC 0,25A / 220V DC					
Protection rating	IP 66	IP 66					
Terminals	NO /NC	NO/NC					



**Response monitoring microswitch** - **KZ** - control of the state of brake (engaged, disengaged),

**Microswitch of the brake lining control – KO** – the microswitch indicates approaching the maximum wear of the brake disc and the necessity of the brake's regulation or replacement of the disc brake, which enables further work of the brake. The regulation procedure is described in the brake operating manual.

KO KZ
SAMPLE INSTALATION

Response monitoring microswitch and microswitch of the brake lining control – KZ+KO

Microswitches set **KZ+KO** is available from type HPSX10 inclusive.

#### PROCTECTIVE CIRCUITS – thermal protection

To protect electromagnet windings against heat build-up (slow-changing overloads) thermal sensor are used. In our offer we have PTC thermistors, which feature high resistance gradients when their rated temperature is reached - posistors - P or bimetallic thermal sensor - B.

Posistor-based sensors are made in the form of an insulated pill with connecting wires extending inside a teflon insulation, installed directly on the electromagnet windings. Sensor circuit terminals are routed outside the brake to the terminal box and connected to a separate connection block or terminal strip. So-called resistance relays are intended for thermistor-based PTC temperature sensors. When temperature of at least one of the sensors rises above the rated value, the circuit resistance suddenly increases triggering the relay.

#### Posistor thermal protection – P

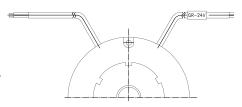
Note! PTC sensor terminals must not be connected directly to the contactor.

The brake protection has the form of a bimetallic sensor. Brake operation is controlled by a sensor or by a set of sensors, which ensure its safe operation; excessive temperature indication is obtained from the thermal switch installed inside the brake electromagnet's housing rated for a specific temperature. When the limit temperature for the sensor is exceeded, the information for the automatic control equipment is sent or the brake circuit is disconnected.

Bimetallic thermal protection – B

#### AUXILIARY CIRCUITS – anti-condensation heaters

The so-called parking heating is used to prevent vapours condensation inside the brake. The equipment is particularly useful in negative temperatures or in high humidity environments. The heater is supplied through its dedicated pair of wires. The heater power supply voltage matches customer requirements. — the need to define the voltage during order.



Anti-condensation heaters - GR -\_\_\_\_V

SAMPLE INSTALATION

K-EN-HPSX-20151203 Page 7 from 8

#### **HPSX**

#### MECHANICAL SIZE

06, 08, 10, 12, 14, 16, 18, 20, 25

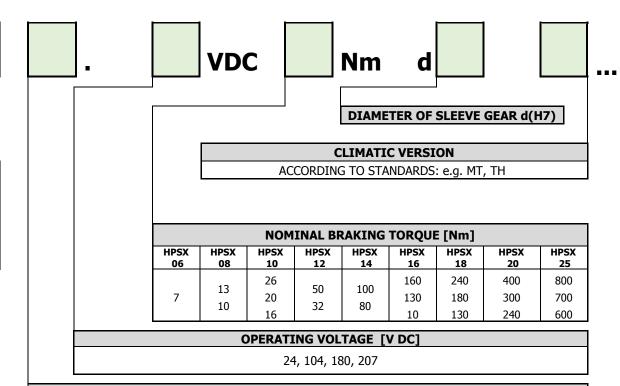
CONFIGURATION	
WITHOUT FITTING / ACCESORIES	1
LEVER FOR MANUAL RELEASE	2
MOUNTING FLANGE	3
LEVER FOR MANUAL RELEASE + MOUNTING FLANGE	4

#### **Execution options for the customer's request:**

- non-standard diameter of the sleeve gear brake d(H7)
- equipped with heating elements in the winding (need to define the voltage supply) – e.g. GR\_\_\_\_V
- work at low temperatures -40°C Z
- posistor thermal protection P
- bimetallic thermal protection B
- other voltage brake
- response monitoring microswitch (engaged, disengaged) - KZ
- microswitch of the brake lining control KO
- microswitches set KZ+KO

#### **EXAMPLE:**

HPSX 12. 30. 180 V DC 32 Nm d25 GR104V HPSX 10. 11. 104 V DC 16 Nm d19 MT HPSX 14. 22. 24VDC 100Nm d25 KZ+KO



# PROTECTION RATING BASIC VERSION – NUT WITH HOLE D4 0 VERSION IP 54 - WITHOUT HOLE D4 1 VERSION IP 54 - NUT WITH D4 + V-RING SEALING 2 VERSION IP 55 - WITHOUT HOLE D4 3 VERSION IP 55 - NUT WITH D4 + V-RING SEALING 4 VERSION IP 56 - WITHOUT HOLE D4 + IP56 BRAKE COVER 5 VERSION IP 56 - NUT WITH D4 + SPECIAL SEALING + IP56 BRAKE COVER 6

The producer reserves the right to modify as a result of developing the product. It is possible to realize special versions.